W1. Objectives, Challenges, State of the Art, Technologies

- Socio-economic context
- Technological evolution of Robotics & State of the Art
- New challenges for Robotics in Human Environments
- Decisional & Control Architecture for Autonomous Mobile Robots & IV
- Sensing technologies: Object Detection
- Sensing technologies: Robot Control & HRI
- Basic technologies for Navigation in Dynamic Human Environments
- Intelligent Vehicles: Context & State of the Art
- Intelligent Vehicles: Technical Challenges & Driving Skills

Place & Role of automobile in our human society

Automobile => Social & Industrial revolution in the 20th century !

The car today *Supposed to be a technological machine designed for enhancing individual Mobility*



For most car owners it's more than that !

✓ Synonymous to **motion freedom**

✓ Often considered as a Precious Personal
 Goods & Showing a particular Social Position

 ✓ Also often synonymous to **Driving Pleasure** (including speed feeling)

✓ Look / Performances & Comfort / Safety are important choice criteria

. . .

But the reality is somewhat different ! (in particular in cities)









A Drastic Future Social & Economic Change

- Huge expected growth of the number of vehicles (3 Billions in 2050) & number of people in cities (75% of population in 2050)
- Human society is no more accepting the nuisances & the incredible socioeconomic cost of traffic accidents (~ 1.2 million fatalities / year in the world)
- Driving Safety is now becoming a major issue for both Governments (Regulation + Supporting plans) & Automotive Industry (Technology + commercial issues)
- New Technologies can strongly help for:
 - Constructing Cleaner & More Intelligent Cars
 - => Next cars generation
 - Developing Sustainable Mobility solutions for smart cities
 - => Cybercars

The good news

Thanks to the last decade advances in the fields of *Robotics & ICT*, Smart Cars & ITS are gradually becoming a reality

→ Driving assistance & Autonomous driving, Passive & Active Safety systems, V2V & V2I communications, Green technologies for reducing fuel consumption & pollution... and also significant advances for **Embedded Perception & Decisional systems**

• Legal issue is also progressively addressed by Governmental authorities

→June 22, 2011: Law Authorizing Driverless Cars on Nevada roads ... Law also adopted later on by California and some other states in USA

→Some other countries (including Europe, Japan...) are also currently analyzing the **way to adapt the legislation** to this new generation of cars

Steps towards "Automated Road" The Automotive approach (Advanced Driver Assistance Systems)



• From ADAS to Fully Autonomous Driving

Numerous R&D projects in the world since about 30 years: AHS in Japan; Path & IVI in USA; Prometheus, Chauffeur, Carsense ... in Europe

Steps towards "Automated Road" The "Cybercar" approach (Autonomous Vehicles in protected areas)



• Medium speed (e.g. 4m/s, 4 times average speed of classical mobile robots)

• From protected areas to progressively more open areas

Several R&D projects since about 2 decades: ICVS in Japan Praxitele, Parkshuttle, Cybercars ... in Europe



State of the Art Cybercar technologies for Sustainable Mobility

- An EU driven concept since the 90's: "Cybercar"
 - Autonomous Self Service Urban & Green Vehicles
 - Numerous R&D projects in Europe during more than 2 decades
 - Several European cities involved
 - Some commercial products already exist for protected areas (e.g. airports, amusement parks...), SME Robosoft, 2GetThere ...



Cycab (Inria /Robosoft)



Cybergo (Induct)



Parkshuttle Schiphol Airport (1997)

State of the Art Cybercar technologies for Sustainable Mobility

• Several early large scale public experiments in Europe



Cybus experiment, La Rochelle 2012, 3 months (CityMobil EU project & Inria)

State of the Art Fully Autonomous Driving

- More than 25 years of research, both for off-road & road Vehicles
 - Significant recent steps towards fully autonomous driving
 > Partly pushed forward by events such as DARPA Grand & Urban Challenges ... and Google Car project
 - Fully Autonomous driving is gradually becoming a reality, for both the Technical & Industrial & Legal point of views
 => e.g. Car industry announcements & Recent Nevada law for driverless cars

State of the Art Fully Autonomous Driving

- Several major events & results
 - Darpa Grand Challenge 2004 & Urban Challenge 2007
 - Intercontinental Autonomous Challenge 2010 (VIAC)
 - Google car project



VIAC Challenge 2010 (Parma – Shanghai) 13 000 km covered, 3 months race, Leader + Followers => See Spring 2011 IEEE RAM issue



State of the Art Advanced Driving Assistance Systems (ADAS)

- Increasing number of Products & Equipped commercial cars
- Traded by Automotive Constructors & Often developed by Car Suppliers







Intelligent Cars – Towards Driverless Cars?

Horizon 2025-30?

Nissan promises a driverless car for 2020

LE FIGARO 29/08/2013



Autonomous car: An industrial challenge for tomorrow ! French Minister of Industry & Carlos Ghosn (PDG Renault-Nissan)



Google Car 2011 140 000 miles covered



Toyota Automated Highway Driving Assist Demo Tokyo 2013, Product 2017 ?



But also most of the Automotive Constructors !

e.g. Tesla (90% Autonomous in 2016), Volvo, Mercedes Class S, BMW

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